PHYS 480/581 General Relativity

Homework Assignment 3 Solutions

Question 1 (7 points).

Imagine we have a tensor (matrix) $X^{\mu\nu}$ and a vector V^{μ} , with components

$$X^{\mu\nu} = \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix}, \qquad V^{\mu} = (-1, 2, 0, -2).$$
(1)

Assuming that these two objects live in flat spacetime with a Minkowski metric $\eta_{\mu\nu}$, find the components of:

(a) $X^{\mu}_{\ \nu}$

Solutions:

$$X^{\mu}_{\ \nu} = X^{\mu\alpha}\eta_{\alpha\nu} = \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} -2 & 0 & 1 & -1 \\ 1 & 0 & 3 & 2 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & -2 \end{pmatrix}$$
(2)

(b) X_{μ}^{ν} Solutions:

$$X_{\mu}^{\ \nu} = \eta_{\mu\alpha} X^{\alpha\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix} = \begin{pmatrix} -2 & 0 & -1 & 1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix}$$
(3)

(c)
$$X^{(\mu\nu)} \equiv \frac{1}{2} (X^{\mu\nu} + X^{\nu\mu})$$

Solutions:

$$X^{(\mu\nu)} = \frac{1}{2} \left(\begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix} + \begin{pmatrix} 2 & -1 & -1 & -2 \\ 0 & 0 & 1 & 1 \\ 1 & 3 & 0 & 1 \\ -1 & 2 & 0 & -2 \end{pmatrix} \right) = \begin{pmatrix} 2 & -\frac{1}{2} & 0 & -\frac{3}{2} \\ -\frac{1}{2} & 0 & 2 & \frac{3}{2} \\ 0 & 2 & 0 & \frac{1}{2} \\ -\frac{3}{2} & \frac{3}{2} & \frac{1}{2} & -2 \end{pmatrix}.$$

$$(4)$$

(d)
$$X_{[\mu\nu]} \equiv \frac{1}{2} (X_{\mu\nu} - X_{\nu\mu})$$

Solutions: First, let's find $X_{\mu\nu}$

$$X_{\mu\nu} = \eta_{\mu\alpha} X^{\alpha\beta} \eta_{\beta\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(5)
$$= \begin{pmatrix} 2 & 0 & -1 & 1 \\ 1 & 0 & 3 & 2 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & -2 \end{pmatrix}.$$
(6)

Thus,

$$X_{[\mu\nu]} = \frac{1}{2} \left(\begin{pmatrix} 2 & 0 & -1 & 1 \\ 1 & 0 & 3 & 2 \\ 1 & 1 & 0 & 0 \\ 2 & 1 & 1 & -2 \end{pmatrix} - \begin{pmatrix} 2 & 1 & 1 & 2 \\ 0 & 0 & 1 & 1 \\ -1 & 3 & 0 & 1 \\ 1 & 2 & 0 & -2 \end{pmatrix} \right) = \begin{pmatrix} 0 & -\frac{1}{2} & -1 & -\frac{1}{2} \\ \frac{1}{2} & 0 & 1 & \frac{1}{2} \\ 1 & -1 & 0 & -\frac{1}{2} \\ \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} & 0 \end{pmatrix}.$$
 (7)

(e) $X^{\lambda}_{\ \lambda}$ Solutions:

$$X^{\lambda}_{\ \lambda} = X^{\lambda\alpha}\eta_{\alpha\lambda} = \operatorname{Tr}\left[\begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix}\begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}\right] = -4.$$
(8)

(f) $V^{\mu}V_{\mu}$

Solutions:

$$V^{\mu}V_{\mu} = \eta_{\mu\nu}V^{\mu}V^{\nu} = -(V^{0})^{2} + (V^{1})^{2} + (V^{2})^{2} + (V^{3})^{2} = 7.$$
(9)

(g) $V_{\mu}X^{\mu\nu}$

Solutions:

$$V_{\mu}X^{\mu\nu} = V^{\alpha}\eta_{\alpha\mu}X^{\mu\nu} = (-1, 2, 0, -2) \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 2 & 0 & 1 & -1 \\ -1 & 0 & 3 & 2 \\ -1 & 1 & 0 & 0 \\ -2 & 1 & 1 & -2 \end{pmatrix}$$
(10)
= (4, -2, 5, 7). (11)

Question 2 (2 points).

The electromagnetic Lagrangian density is $\mathcal{L} = -\frac{1}{4}F_{\mu\nu}F^{\mu\nu}$. With the help of Eq. (4.14) in Moore, write down \mathcal{L} in terms of the \vec{E} and \vec{B} field components. **Solutions:** First, the components of $F_{\mu\nu}$ are given by

$$F_{\mu\nu} = \eta_{\mu\alpha} F^{\alpha\beta} \eta_{\beta\nu} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 & E_x & E_y & E_z \\ -E_x & 0 & B_z & -B_y \\ -E_y & -B_z & 0 & B_x \\ -E_z & B_y & -B_x & 0 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$
(12)

and thus

$$F_{\mu\nu} = \begin{pmatrix} 0 & -E_x & -E_y & -E_z \\ E_x & 0 & B_z & -B_y \\ E_y & -B_z & 0 & B_x \\ E_z & B_y & -B_x & 0 \end{pmatrix}$$
(13)

$$\mathcal{L} = -\frac{1}{4}F_{\mu\nu}F^{\mu\nu} = -\frac{1}{4}\left(F_{0i}F^{0i} + F_{i0}F^{i0} + F_{ij}F^{ij}\right)$$
(14)

$$= -\frac{1}{4} \left(2F_{0i}F^{0i} + 2\sum_{j>i} F_{ij}F^{ij} \right), \tag{15}$$

where we use the antisymmetric nature of $F^{\mu\nu}$ to realize that $F_{0i}F^{0i} = F_{i0}F^{i0}$. Thus

$$\mathcal{L} = -\frac{1}{2} \left(-E_x^2 - E_y^2 - E_z^2 + B_x^2 + B_y^2 + B_z^2 \right)$$
(16)

$$= \frac{1}{2} \left(|\vec{E}|^2 - |\vec{B}|^2 \right). \tag{17}$$

Question 3 (5 points).

Moore Problem 5.5 Solutions:

(a) Lines of constant u and w looks like this:



Figure 1: Lines of constant u and w in cartesian coordinates.

(b) The metric in the primed (u, w) coordinates is

$$g_{\alpha\beta}' = \frac{\partial x^{\mu}}{\partial x'^{\alpha}} \frac{\partial x^{\nu}}{\partial x'^{\beta}} \eta_{\mu\nu}, \qquad (18)$$

where $\eta_{\mu\nu}$ is the Minkowski metric. The inverse relation between the cartesian coordinates and the (u, w) coordinates are

$$x = u, \qquad y = w + A\sin\left(bu\right). \tag{19}$$

Let's work out each component separately.

$$g'_{uu} = \left(\frac{\partial x}{\partial u}\right)^2 \eta_{xx} + \left(\frac{\partial y}{\partial u}\right)^2 \eta_{yy} \tag{20}$$

$$= 1 + A^2 b^2 \cos^2(bu)$$
 (21)

$$g'_{uw} = g'_{wu} = \frac{\partial x}{\partial u} \frac{\partial x}{\partial w} \eta_{xx} + \frac{\partial y}{\partial u} \frac{\partial y}{\partial w} \eta_{yy}$$
(22)

$$=Ab\cos\left(bu\right)\tag{23}$$

$$g'_{ww} = \left(\frac{\partial x}{\partial w}\right)^2 \eta_{xx} + \left(\frac{\partial y}{\partial w}\right)^2 \eta_{yy} \tag{24}$$

$$=1$$
(25)

Thus, the metric in the (u, w) coordinate system is

$$g'_{\alpha\beta} = \begin{pmatrix} 1 + A^2 b^2 \cos^2(bu) & Ab \cos(bu) \\ Ab \cos(bu) & 1 \end{pmatrix}.$$
 (26)

This metric is *not* diagonal.

(c) The transformation property for a vector is

$$v^{\prime\alpha} = \frac{\partial x^{\prime\alpha}}{\partial x^{\mu}} v^{\mu},\tag{27}$$

with $v^x = v$ and $v^y = 0$. We thus have

$$v'^{u} = \frac{\partial u}{\partial x} v^{x} = v \tag{28}$$

$$v'^{w} = \frac{\partial w}{\partial x}v^{x} = -Ab\cos\left(bx\right)v = -Abv\cos\left(bvt\right).$$
(29)

(d) The inner product $v \cdot v$ should be the same the same in every frame. In the cartesian frame it is of course $v \cdot v = v^2$. In the (u, w) frame, it is given by

$$\boldsymbol{v} \cdot \boldsymbol{v} = g'_{\alpha\beta} v'^{\alpha} v'^{\beta} \tag{30}$$

$$=g'_{uu}(v'^{u})^{2} + 2g'_{uw}v'^{u}v'^{w} + g'_{ww}(v'^{w})^{2}$$
(31)

$$= (1 + A^{2}b^{2}\cos^{2}(bu))v^{2} + 2Ab\cos(bu)v(-Abv\cos(bvt)) + (-Abv\cos(bvt))^{2}$$
(32)
$$= (1 + A^{2}b^{2}\cos^{2}(but))v^{2} + 2Ab\cos(bu)v(-Abv\cos(bvt)) + (-Abv\cos(bvt))^{2}$$
(32)

$$= v^{2} + A^{2}b^{2}v^{2}\cos^{2}(bvt) - 2A^{2}b^{2}v^{2}\cos^{2}(bvt) + A^{2}b^{2}v^{2}\cos^{2}(bvt)$$
(33)

$$=v^2,$$
(34)

where we used u = x = vt. So, of course, the inner product $v \cdot v$ is the same in the (u, w) frame. v'^w is not a constant since the $\mathbf{e}_{(u)}$ basis vector keeps changing direction as one moves in the (x, y) plane, which should be apparent from Fig. 1. Since the vector v is constant, the component v'^w has to keep changing to compensate for the fact that the $\mathbf{e}_{(u)}$ basis vector changes from point to point.

(e) Since v is a constant vector, then we must have a = dv/dt = 0. This is obviously true in the cartesian system. But we know that

$$\frac{dv'^w}{dt} = Ab^2 v^2 \sin\left(bvt\right) \neq 0. \tag{35}$$

So, if we were to write

$$\boldsymbol{a} \stackrel{?}{=} \frac{dv'^{u}}{dt} \mathbf{e}_{(u)} + \frac{dv'^{w}}{dt} \mathbf{e}_{(w)} = \frac{dv'^{w}}{dt} \mathbf{e}_{(w)} \neq 0,$$
(36)

we would get something nonzero, in contradiction with the fact that v is a constant vector. To resolve this, we need to remember that $\mathbf{e}_{(u)}$ is not a constant vector. This means that the acceleration is really given by

$$\boldsymbol{a} = \frac{d}{dt} \left(v^{\prime u} \mathbf{e}_{(u)} + v^{\prime w} \mathbf{e}_{(w)} \right) \tag{37}$$

$$=\frac{dv'^{u}}{dt}\mathbf{e}_{(u)}+v'^{u}\frac{d\mathbf{e}_{(u)}}{dt}+\frac{dv'^{w}}{dt}\mathbf{e}_{(w)}+v'^{w}\frac{d\mathbf{e}_{(w)}}{dt}$$
(38)

$$=v^{\prime u}\frac{d\mathbf{e}_{(u)}}{dt}+\frac{dv^{\prime w}}{dt}\mathbf{e}_{(w)}.$$
(39)

Now, both of the terms in the last line are not zero. In fact, they are equal and opposite, resulting in a = 0 as it should. So indeed, dv'^w/dt is not the *w*-component of the acceleration.